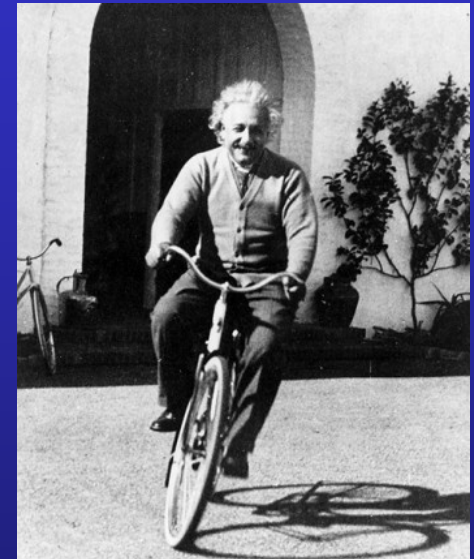


Classical Mechanics

PHYS 2006

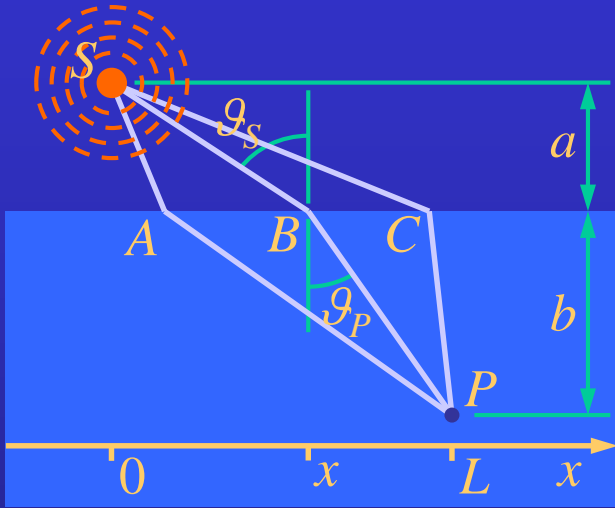
Tim Freegarde



Classical Mechanics

LINEAR MOTION OF SYSTEMS OF PARTICLES	centre of mass
	Newton's 2nd law for bodies (internal forces cancel)
	rocket motion
ANGULAR MOTION	rotations and infinitesimal rotations
	angular velocity vector, angular momentum, torque
	parallel and perpendicular axis theorems
	rigid body rotation, moment of inertia, precession
GRAVITATION & KEPLER'S LAWS	conservative forces, law of universal gravitation
	2-body problem, reduced mass
	planetary orbits, Kepler's laws
	energy, effective potential
NON-INERTIAL REFERENCE FRAMES	centrifugal and Coriolis terms
	Foucault's pendulum, weather patterns
NORMAL MODES	coupled oscillators, normal modes
	boundary conditions, Eigenfrequencies

Fermat's principle of least time

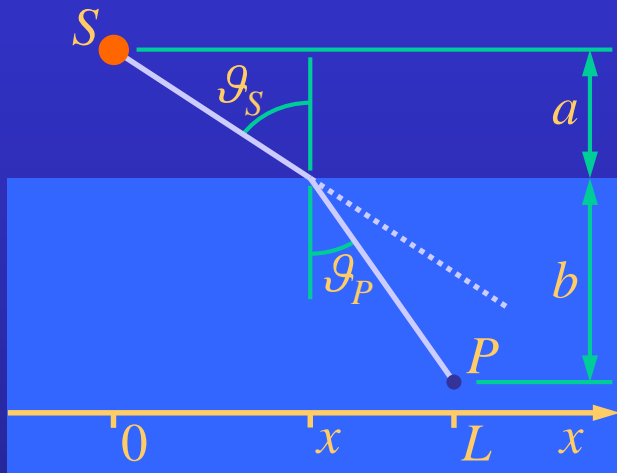


- refraction at a plane surface



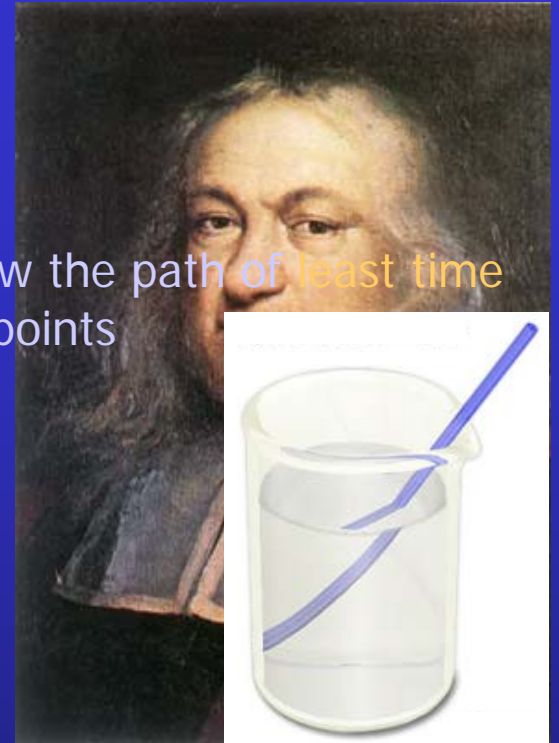
Pierre de Fermat (1601-1665)

Fermat's principle of least time



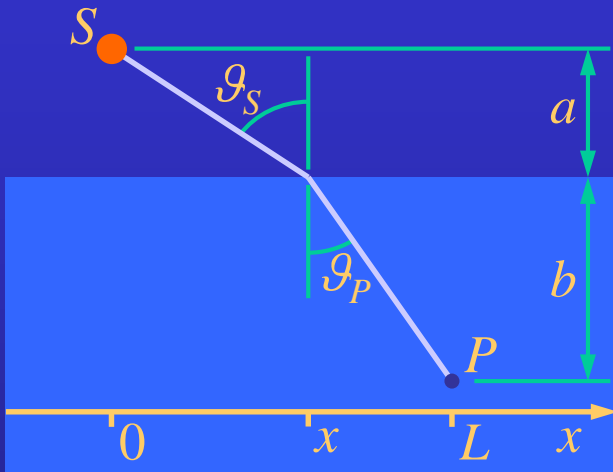
- refraction at a plane surface

- light rays follow the path of least time between two points



Pierre de Fermat (1601-1665)

Snell's law of refraction



- refraction at a plane surface

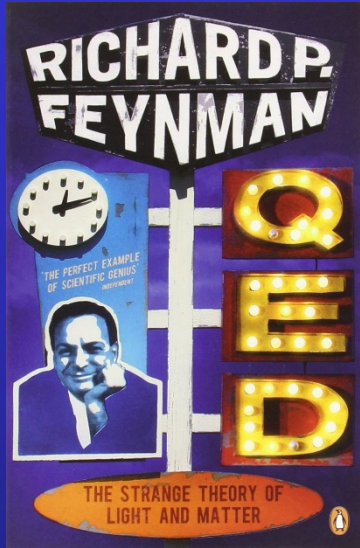
- light rays follow the path of **least time** between two points

$$\eta_S \sin \vartheta_S = \eta_P \sin \vartheta_P$$



Willebrord Snel van Royen
(Leiden, 1580-1626)

Feynman path integral



PRINCIPLE OF LEAST ACTION

- trajectory is that which minimizes

$$S = \int_{t_1}^{t_2} \mathcal{L} dt \quad \text{ACTION}$$

where $\mathcal{L} = \mathcal{T} - \mathcal{V}$ LAGRANGIAN



Richard P Feynman (1918-1988)

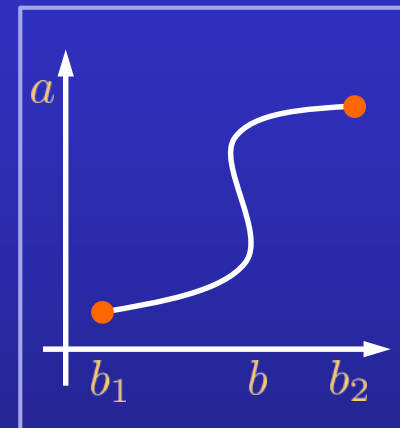
Lagrangian Mechanics

CALCULUS OF VARIATIONS

if $\mathcal{F}(a, a')$ has been chosen to minimize

$$\mathcal{S} = \int_{b_1}^{b_2} \mathcal{F}(a, a') db \quad \text{least (or stationary) action}$$

then $\frac{\partial \mathcal{F}}{\partial a} - \frac{d}{db} \left(\frac{\partial \mathcal{F}}{\partial a'} \right) = 0$ EULER-LAGRANGE EQUATION

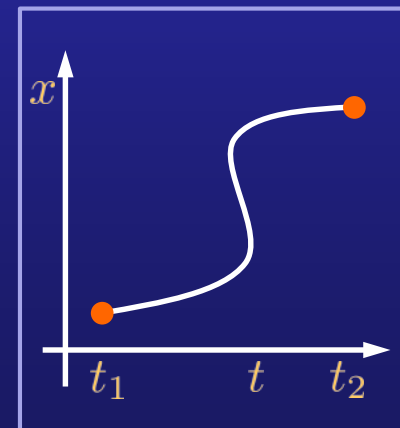


LAGRANGIAN MECHANICS

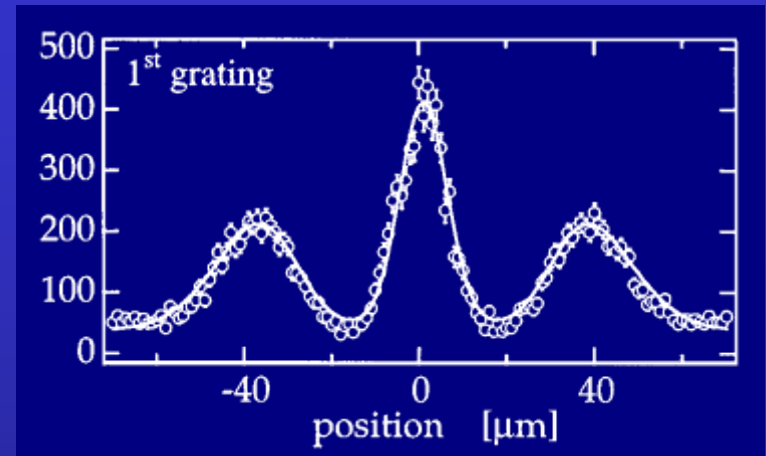
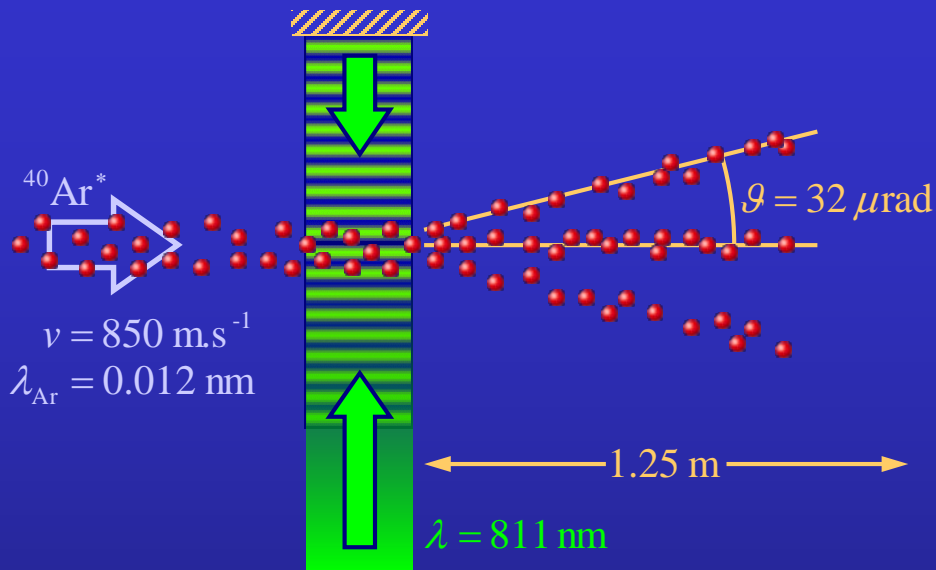
set $\mathcal{F} \rightarrow \mathcal{L} = \mathcal{T} - \mathcal{V}$

$a \rightarrow x, y, \vartheta$ etc. (coordinate variables)

$b \rightarrow t$



Diffraction atoms

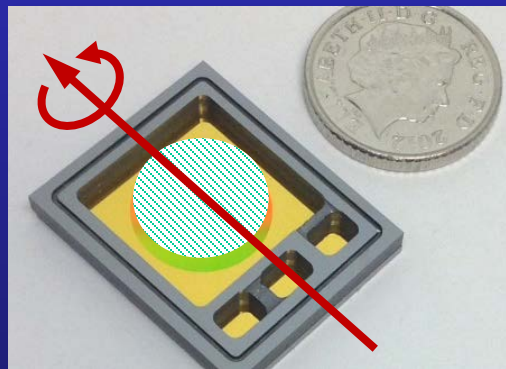
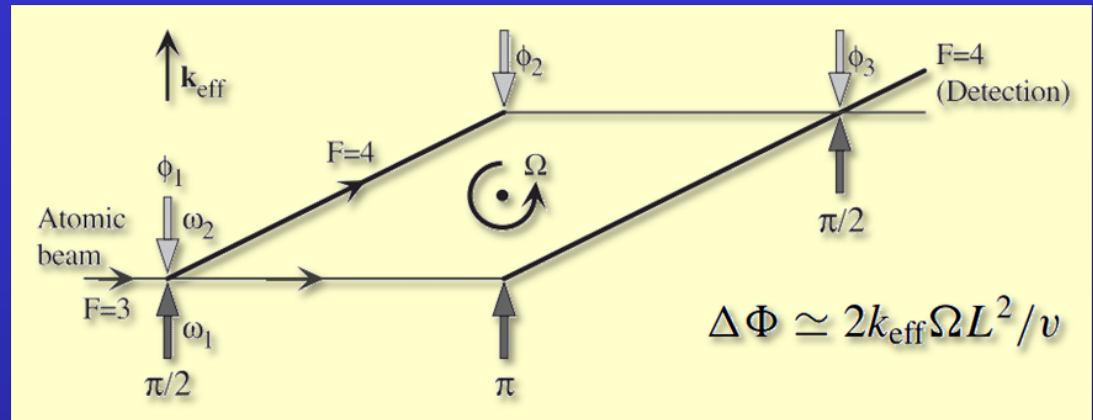


E M Rasel et al, Phys Rev Lett **75** 2633 (1995)

- stimulated Raman transitions equivalent to Bragg scattering from moving standing wave

Inertial sensing using light

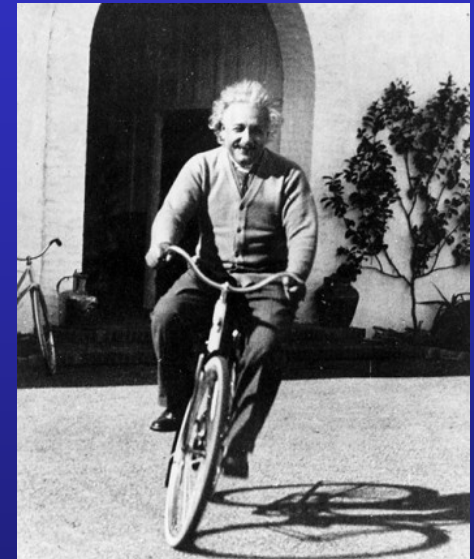
- Mach-Zehnder interferometer
- quantum wavefunction split and recombined
- laser-cooled atoms sense inertial Coriolis acceleration
- phase depends upon rotation



Classical Mechanics

PHYS 2006

Tim Freegarde



QUESTION TERMINOLOGY

- State, What, Identify, Express, Find
 - no derivation required
- Explain, Describe, How
 - in words...
- Derive, Prove, Show that, Determine
 - state assumptions, proceed logically
- Evaluate, Indicate, Calculate, Estimate
 - numbers, with clear assumptions
- Sketch
 - as it says...

DEGREE CLASSIFICATIONS

- **First class (70%)**
 - Ability to extend or adapt standard derivations & manipulations to unseen problems
 - Demonstrate good insight & knowledge beyond course material
- **2:1 (60%)**
 - Recall of standard derivations, manipulations & examples
 - Ability to discuss critically & demonstrate some insight
- **2:2 (50%)**
 - Recall of simple derivations, manipulations & examples
 - Some ability to discuss critically
- **Third (40%)**
 - Knowledge of basic definitions, formulae, phenomena & examples
 - Ability to apply formulae directly

Classical Mechanics

PHYS 2006

Tim Freegarde

